

Bayesian Model-Based Clustering for Dynamic Count Networks

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Focus of this Talk

This talk aims at introducing Dynamic Count Networks (DCN) and as well as presenting a Bayesian Latent Space Model for community detection (clustering) in DCN.

The presentation consists predominantly of:

- Introduction to Dynamic Count Networks
- Definition of a Latent Space Model for DCN clustering
- Model parameter estimation using Bayesian inference
- Simulation of a DCN and model implementation

What is a Count Network?

Count Network Definition

Count Network is a mathematical structure, that uses count data (e.g. emails, calls) to describe pairwise relations between objects. It consists of vertices and the number of events between them.

Count Adjacency Matrix Definition

The count adjacency matrix Y for a count network of N nodes is an $N \times N$ matrix of which each cell is defined as:

$$y_{ij} = \left\{ \begin{array}{l} \text{number of events between the } i^{\text{th}} \text{ and } j^{\text{th}} \\ \text{actors of the network .} \end{array} \right\}$$

What is a Dynamic Count Network?

Dynamic Count Network (DCN) Definition

Dynamic Count Network (DCN) is a count network, that changes over time and can be described by a count adjacency cube Y , where:

$$y_{ij}^{(t)} = \left\{ \begin{array}{l} \text{number of events between the } i^{\text{th}} \text{ and } j^{\text{th}} \\ \text{actors of the network at time } t. \end{array} \right\}$$

Outline

- 1 Introduction
- 2 Theoretical Background**
- 3 Bayesian Estimation
- 4 Implementation
- 5 Conclusions
- 6 References

Model Definition

- ▶ We assume that the event rates between the i^{th} and j^{th} actors of the network at time t can be modelled as:

$$\log(\lambda_{ij}^{(t)}) = \gamma^{(t)} \mathbb{1}_{\{y_{ij}^{(t-1)} - y_{ij}^{(t-2)} > 0\}} + \delta^{(t)} \mathbb{1}_{\{y_{ij}^{(t-1)} - y_{ij}^{(t-2)} \leq 0\}} - |W_i - W_j|$$

where, $\gamma^{(t)}$ is an increasing count parameter and $\delta^{(t)}$ a decreasing-stable count parameter. W_i refers to the network actors latent positions in a d -dimensional Euclidean space and $|\cdot|$ is the Euclidean norm.

- ▶ We can express the likelihood of the above model as:

$$\mathcal{L}_y = \prod_{t=3}^T \prod_{i=1}^N \prod_{j:i < j}^N \{Poisson(\lambda_{ij}^{(t)})\}$$

Model Definition

- ▶ To represent clustering, we assume that W_i 's are drawn from a finite mixture of G multivariate normal distributions (FMG). Each MVN has a different mean vector and a spherical covariance matrix with variances, that differ between groups:

$$W_i \sim \sum_{g=1}^G \pi_g \text{MVN}_d(\mu_g, \sigma_g^2 \mathbf{I}_d)$$

where, π_g is the probability that an actor belongs to the g^{th} group, so that $\pi_g \geq 0$ and $\sum_{g=1}^G \pi_g = 1$.

Outline

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- 3 Bayesian Estimation**
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Prior Distributions

- For the FMG part of the model, we introduce a new variable k_i equal to g if the i^{th} actor belongs to the g^{th} group as is standard in Bayesian estimation of mixture models.

$$\pi \sim \text{Dirichlet}(\nu)$$

$$\sigma_g^2 \sim \sigma_0^2 \text{Inv}\chi_\alpha^2$$

$$\mu_g \sim \text{MVN}_d(0, \omega^2 \mathbf{I}_d)$$

and

$$P(W, K | \pi_g, \mu_g, \sigma_g^2) = \prod_{g=1}^G \prod_{i=1}^N (\pi_g N_d(\mu_g, \sigma_g^2 \mathbf{I}_d))^{\mathbb{1}_{\{k_i=g\}}}$$

Prior Distributions

- For the parameters γ and δ we assume random walk priors:

$$f(\gamma|\tau_\gamma, \tau_\gamma^0) = f\left(\gamma^{(1)}; 0, \frac{1}{\tau_\gamma^0}\right) \prod_{t=2}^T f\left(\gamma^{(t)}; \gamma^{(t-1)}, \frac{1}{\tau_\gamma}\right)$$

$$f(\delta|\tau_\delta, \tau_\delta^0) = f\left(\delta^{(1)}; 0, \frac{1}{\tau_\delta^0}\right) \prod_{t=2}^T f\left(\delta^{(t)}; \delta^{(t-1)}, \frac{1}{\tau_\delta}\right)$$

where, $f(x; m, v)$ is a Gaussian density estimated at x with mean m and variance v .

- For the prior information of the precision parameters $\tau_\gamma, \tau_\gamma^0, \tau_\delta, \tau_\delta^0$ we propose a *Gamma*(A, B) density.

Posterior Distributions

The full conditional posterior distributions are:

- $W_i | K_i = g, \text{others} \propto \phi_d(w_i; \mu_g, \sigma_g^2 \mathbf{I}_d) \times P(Y | W, \beta, \gamma, \delta)$
- $\pi | \text{others} \propto \text{Dirichlet}(m + \nu)$
- $\mu_g | \text{others} \propto \text{MVN}_d \left(\frac{\mu_g \bar{w}_g}{\mu_g + \sigma_g^2 / \omega^2}, \frac{\sigma_g^2}{\mu_g + \sigma_g^2 / \omega^2} \mathbf{I} \right)$
- $\sigma_g^2 | \text{others} \propto \left(\frac{\sigma_0^2 + d s_g^2}{\alpha + \mu_g d} \right) \text{Inv} \chi_{\alpha + \mu_g d}^2$
- $P(K_i = g | \text{others}) = \frac{\pi_g \phi_d(w_i; \mu_g, \sigma_g^2 \mathbf{I}_d)}{\sum_{r=1}^G \phi_d(w_i; \mu_r, \sigma_r^2 \mathbf{I}_d)}$

where,

$$m_g = \sum_{i=1}^n \mathbb{1}_{\{K_i=g\}}$$
$$s_g^2 = \frac{1}{d} \sum_{i=1}^n (w_i - \mu_g)^T (w_i - \mu_g) \mathbb{1}_{\{K_i=g\}}$$
$$\bar{w}_g = \frac{1}{m_g} \sum_{i=1}^n w_i \mathbb{1}_{\{K_i=g\}}$$

Posterior Distributions

- $\gamma^{(t)} | \text{others} \propto P(Y|W, \beta, \gamma, \delta) \times$
 $f(\gamma^{(t)}; 0, \frac{1}{\tau_\gamma^0})^{\mathbb{1}_{\{t=1\}}} f(\gamma^{(t)}; \gamma^{(t-1)}, \frac{1}{\tau_\gamma})^{\mathbb{1}_{\{t>1\}}} f(\gamma^{(t+1)}; \gamma^{(t)}, \frac{1}{\tau_\gamma})^{\mathbb{1}_{\{t<T\}}}$
- $\delta^{(t)} | \text{others} \propto P(Y|W, \beta, \gamma, \delta) \times$
 $f(\delta^{(t)}; 0, \frac{1}{\tau_\delta^0})^{\mathbb{1}_{\{t=1\}}} f(\delta^{(t)}; \delta^{(t-1)}, \frac{1}{\tau_\delta})^{\mathbb{1}_{\{t>1\}}} f(\delta^{(t+1)}; \delta^{(t)}, \frac{1}{\tau_\delta})^{\mathbb{1}_{\{t<T\}}}$
- $\tau_\gamma \sim \text{Gamma}\left(A + \frac{T-1}{2}, B + \frac{\sum_{t=1}^T (\gamma^{(t)} - \gamma^{(t-1)})^2}{2}\right)$
- $\tau_\gamma^0 \sim \text{Gamma}\left(A + \frac{1}{2}, B + \frac{(\gamma^{(1)})^2}{2}\right)$
- $\tau_\delta \sim \text{Gamma}\left(A + \frac{T-1}{2}, B + \frac{\sum_{t=1}^T (\delta^{(t)} - \delta^{(t-1)})^2}{2}\right)$
- $\tau_\delta^0 \sim \text{Gamma}\left(A + \frac{1}{2}, B + \frac{(\delta^{(1)})^2}{2}\right)$

MCMC Algorithm

- Step 1:** use of Metropolis-Hastings algorithm to sample $W_i, \forall i = 1, \dots, N$, setting as a proposal density a d-variate Gaussian distribution $N_d(w_{old}, \delta_w^2 I_d)$.
- Step 2:** use of Gibbs sampling algorithm to generate samples for μ_g, σ_g^2 and π_g .
- Step 3:** use of random walk Metropolis algorithm to update the constant parameters γ and δ .
- Step 4:** use of Gibbs sampling algorithm to sample from the conjugate posterior densities of $\tau_\gamma, \tau_\gamma^0, \tau_\delta, \tau_\delta^0$.

Label Switching Problem

For Bayesian mixtures the invariance of the likelihood to permutations in the labelling is referred to as *label switching problem*.

ECR Algorithm (Papastamoulis and Iliopoulos, 2010)

It is based on the idea that equivalent allocation vectors are mutually exclusive from the label switching solution.

- 1 Define a pivot allocation vector $k^* = (k_1^*, \dots, k_N^*)$. The pivot is selected by choosing a high-posterior density point.
- 2 For $iter = 1, \dots, N_{iter}$ find a permutation $p^{(iter)} \in \mathcal{P}$ that maximizes $\sum_{i=1}^N \mathbb{1}_{\{pk_{iter}^* = k_i^*\}}$

Choosing the number of clusters

- BIC approximation for the dynamic Poisson regression part of the model:

$$BIC_{DPR} = 2 \log[P\{Y|\hat{W}, \hat{\gamma}, \hat{\delta}\}] - 2T \log\left(\frac{TN(N-1)}{2}\right)$$

- BIC approximation for the FMG part of the model:

$$BIC_{FMG} = 2 \log[P\{\hat{W}|\hat{\theta}\}] - d_{FMG} \log(N)$$

where, d_{FMG} is the number of parameters in the clustering model and N the number of actors.

- BIC approximation for the entire model:

$$BIC = BIC_{DPR} + BIC_{FMG}$$

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Simulation

Step 1: Assume that the network has the following fundamental properties $G = 3$, $d = 2$, $T = 20$ and $N = 100$.

Step 2: Generate samples for the actors latent positions W using as mixture proportions $\pi_g = (1/4, 1/2, 1/4)$, clusters centres $\mu_1 = (-3, -3)$, $\mu_2 = (0, 0)$, $\mu_3 = (3, 3)$ and variances $\sigma_g^2 = (0.4^2, 0.2^2, 0.3^2)$.

Step 3: Generate samples for the constant parameters $\gamma^{(t)}$ and $\delta^{(t)}$ using a random walk process.

$$\gamma^{(t)} \sim N(\gamma^{(t-1)}, 1/2)$$

$$\delta^{(t)} \sim N(\delta^{(t-1)}, 1/2)$$

Simulation

Step 4: For $t = 1, 2$ we have that:

$$Y_{ij}^{(t)} \sim \text{Poisson}\left(\frac{1}{|W_i - W_j|}\right)$$

and for $t = 3, \dots, T$

$$Y_{ij}^{(t)} \sim \text{Poisson}(\lambda_{ij}^{(t)})$$

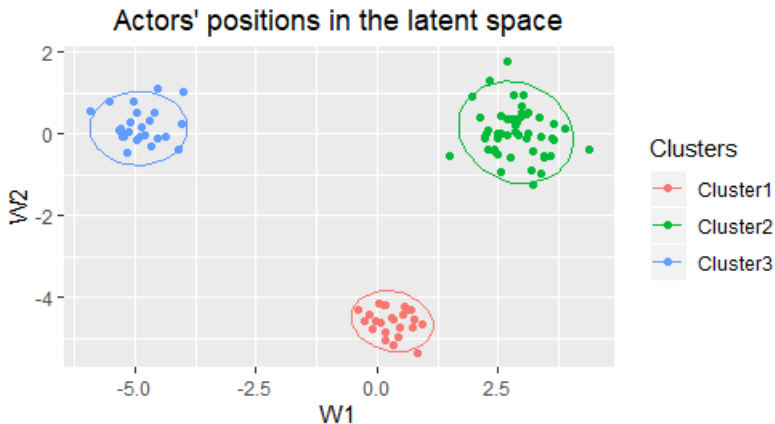
where

$$\lambda_{ij}^{(t)} = \exp\left(\gamma^{(t)} \mathbb{1}_{\{y_{ij}^{(t-1)} - y_{ij}^{(t-2)} > 0\}} + \delta^{(t)} \mathbb{1}_{\{y_{ij}^{(t-1)} - y_{ij}^{(t-2)} \leq 0\}} - |W_i - W_j|\right)$$

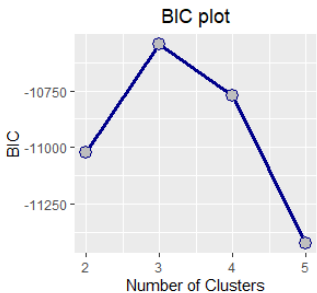
Simulation

Model fitting

The MCMC algorithm ran for 20000 iterations, of which the first 8000 were used as burn in period. The values of the model hyper-parameters were defined as $\delta_W^2 = 1$, $\nu = c(3, 3, 3)$, $\omega^2 = 2$, $\alpha = 2$ and $\sigma_0^2 = 0.1$.



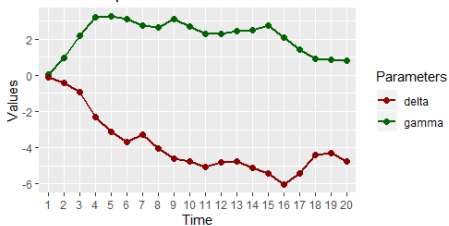
Model fitting



Confusion Matrix of the Laten Space Model



Constant parameters estimation over time



Outline

- 1 Introduction
- 2 Theoretical Background
- 3 Bayesian Estimation
- 4 Implementation
- 5 Conclusions**
- 6 References

Conclusions

- Accurate estimation of the dynamic count network communities.
- Time consuming runs of the MCMC algorithm.
- Difficulty of tuning the hyper-parameters.
- Fitting the DCN latent space model to real data.
- Use of a more time series approach for clustering DCN.

Outline

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- 5 Conclusions
- 6 References**

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